# rnes



## **The Swarm Absolute Scalar Magnetometer**

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#### ASM MAIN MISSION

As the magnetic reference of the ESA Swarm mission, ASM shall provide absolute measurements of the Earth's magnetic field strength, with unequaled performances, independent of the field modulus, the spatial position and orientation :

-Measurement range: [15 µT - 65 µT],

-Scalar bandwidth / sampling rate :

-Standard mode: [0 – 0,4 Hz] / 1 Hz [0 – 100 Hz] / 250 Hz -Burst mode : - for ambient noise level measurement - may also have a scientific interest ?

- Scalar resolution / precision :

- Resolution < 1 pT/ √Hz [DC-100 Hz] demonstrated over the [15 μT 65 μT] range</p>
- **Precision** < 1 pT (Fs = 1 Hz, BW = 0,4 Hz  $\Rightarrow \sigma$  = R \*  $\sqrt{BW}$  < 1 pT)

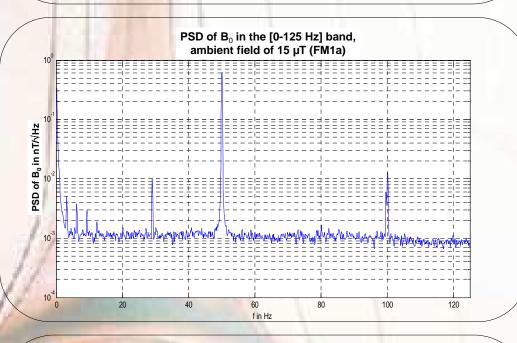
- Scalar accuracy :

- The internal ASM accuracy error sources have been accurately characterized

Maximum accuracy error after correction : σmax : 65 pT

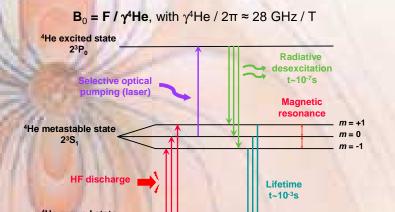
Stability :

· Better than 25 pT over 15 days, demonstrated at Chambon-La-Forêt (IPGP)



### PHYSICAL PRINCIPLE (SCALAR MEASUREMENT)

ASM is a magnetic field to frequency converter based on atomic spectroscopy of the <sup>4</sup>He in its metastable level 2<sup>3</sup>S<sub>1</sub>. The magnetic field modulus B<sub>0</sub> is directly proportional to the magnetometer's resonance frequency F (Zeeman effect) :



#### ASM SIDE MISSION

On an experimental basis, ASM shall provide absolute measurements of the Earth's magnetic field direction, the nominal Swarm vector data being delivered by the VFM.

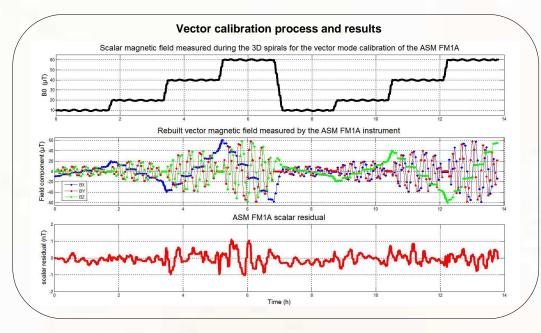
→unique instrument in providing simultaneous absolute scalar & vector measurements at the same point

→auto calibration, permanent quality assessment, stability, no offsets nor drifts Performances (inversely proportional to the field modulus) :

- Measurement range : ± 65 µT
- Sampling rate :
- Bandwidth : [DC- 0,4 Hz]
- Resolution :
- < 1 nT/√Hz at 40 µT - Absolute accuracy  $\leq 1 \text{ nT} (2 \sigma) \text{ at } 40 \mu \text{T}$

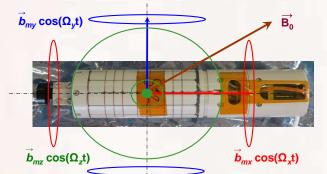
1 Hz

Proven concept on ground, performance to be validated in flight (will depend on the background noise). Swarm will offer a unique opportunity to validate the ASM vector data in orbit by comparing them with the VFM's, thus opening the way for a potential in-space cross calibration.



### PHYSICAL PRINCIPLE (VECTOR MEASUREMENT)

Innovative concept based on the scalar architecture using 3 orthogonal coils: superposition of 3 AC low frequency modulations (amplitude ~ 50 nT) on the static field B<sub>0</sub>, along 3 orthogonal directions. A real time analysis of the resulting scalar measurement, with simple deconvolution operations, provide then simultaneously a direct estimation of the magnetic field projections on the three modulation directions in addition to the static field determination.



<sup>4</sup>He ground state 11S

#### SENSOR'S ISOTROPIC DESIGN

A non magnetic sensor including the 4He cell, based on an isotropic design with a static and a rotating part, optimal resonance conditions controlled by a piezoelectric motor : no dead zones.



### Want to learn more ? http://swarm-mission.cnes.fr

 $\left\|\vec{B}_{tot}\right\| = \left\|\vec{B}_{o} + \sum \vec{b}_{mi} \cos\left(\Omega_{i}t\right)\right\|$ 

#### STATUS

6 ASM instruments are integrated on the 3 Swarm satellites (full cold redundancy), which are ready for shipment to the launch site. The launch from Plessetsk with a Rockot launcher is due by the end of 2013. ASM level 1B products will be validated during the first months following the launch, in close partnership between CNES, CEA-Leti and IPGP.

