









Sequential modelling of the Earth core magnetic field

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IPGP, Geomagnetism

Introduction

- Overall goal: modelling the core's magnetic field and surface flow at small time scales (\leq 1year)
 - Correlation based, sequential data assimilation
 - Co-estimation of the surface flow
- Results: time series of core field models for 2000-2020

• October 1st: IGRF-13 candidate

Sequential modelling approach

Kalman filter:

- Analysis: correlation based bayesian inversion of satellite and observatory data
 - Prior information added through correlation matrices (Holschneider et al, 2016)
 - → Two different approaches for building correlation matrices: Holschneider et al. (2016) or Numerical dynamo experiments (Aubert et al.)
- Prediction: estimation of the model at the next time step. Evolution based on a combination of stochastic prediction and Taylor expansion.
- Smoothing: backward smoothing according to RTS (Anderson and Moore 1979)

Continuous data assimilation : allows for continuous assimilation of new SWARM and observatory data

Analysis process

- Data set covers the satellite era. It includes observatory data, CHAMP satellite data and SWARM-A satellite data. Data are selected for magnetically quiet night times
 - Three months of data are used for each 3-month analysis period.
 - Data weights are evaluated through iterative Huber-weighting
 - Data set spans exactly from 01/01/2000 to 07/31/2019

- For each analysis step are modelled:
 - Static core field (SH degree 1 to 18)
 - SV core field (SH degree 1 to 18)
 - Lithospheric field (SH degree 15 to 30 -- known field subtracted from data for SH 30 to 120)
 - Static external field in GSM coordinate system (SH degree 3)
 - Static external field in SM coordinate system (SH degree 3)
 - Dst dependent fields in SM coordinate systems (SH degree 3)
 - IMFBy dependent field in SM coordinate systems (SH degree 3)
 - Induced field and its time variations in GEO coordinate system (SH degree 6)
 - Observatory offsets (3x195 observatories)

Prediction and smoothing

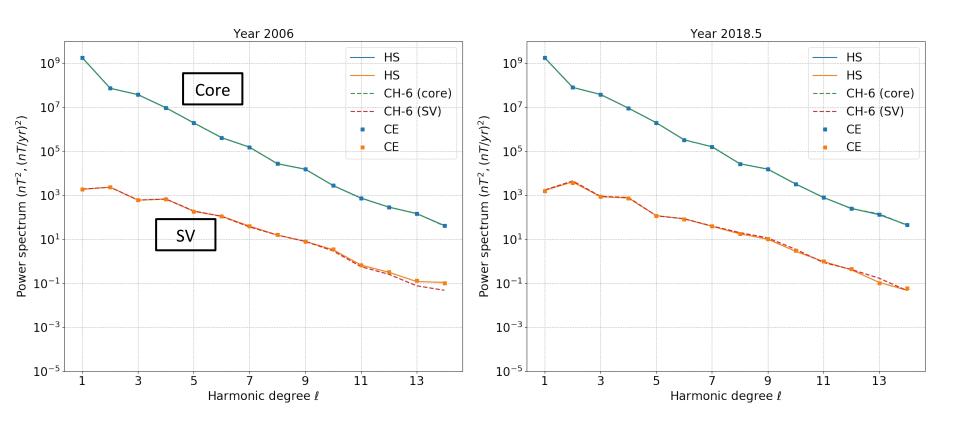
Prediction step:

- Core field: predicted through the SV
- SV: predicted using a stochastic process (timescale ~ 11-15 years)
- External fields: no time correlation
- Lithospheric field: regarded as static (huge timescale)

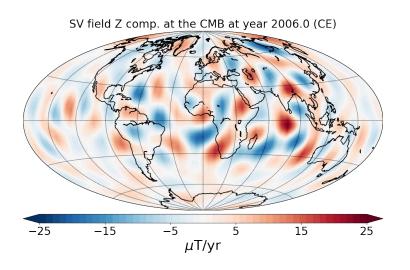
Backward smoothing:

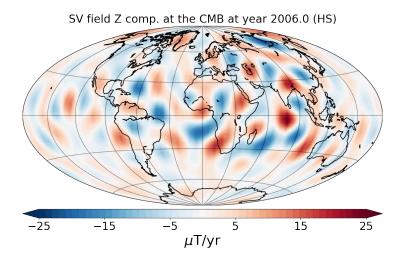
- Performed over the whole era, starting at the last time step.
- Based on the Rauch-Tung-Striebel (RTS) smoother (Anderson and Moore 1979)

Power spectra at years 2006.0 and 2018.5 (Earth's surface)

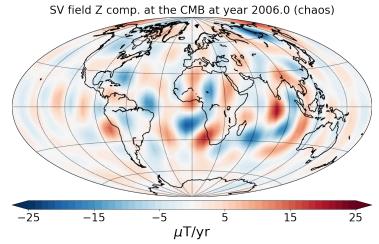


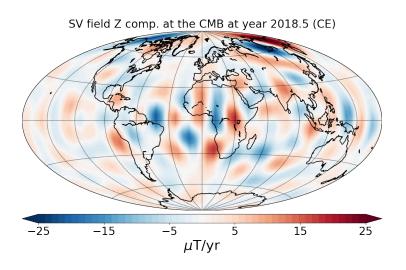
Chaos model: Chaos 6x9

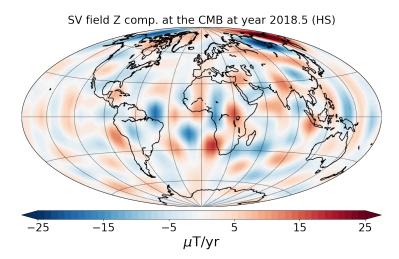




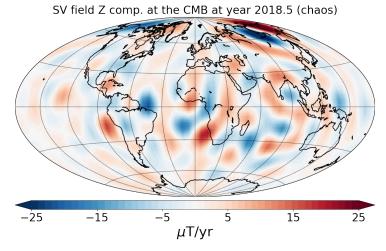
Lmax = 14



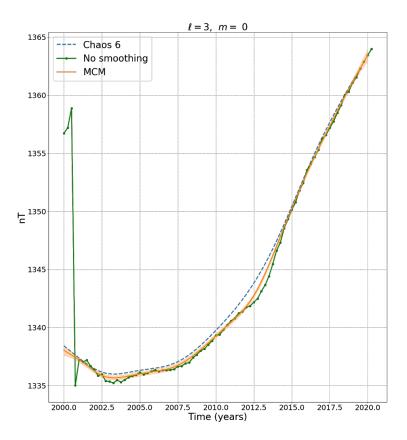


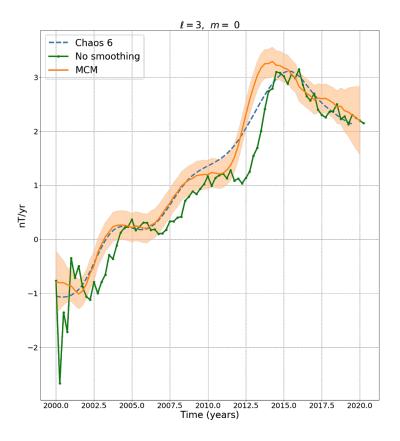


Lmax = 14



• Times series (*Holschneider* prior)

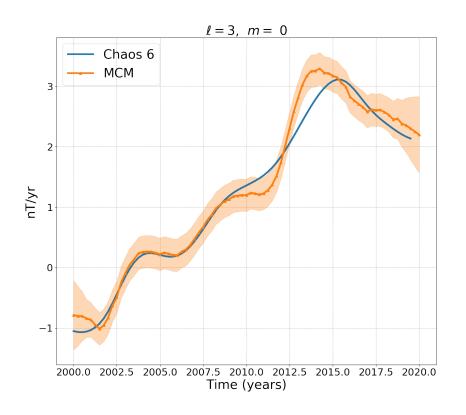


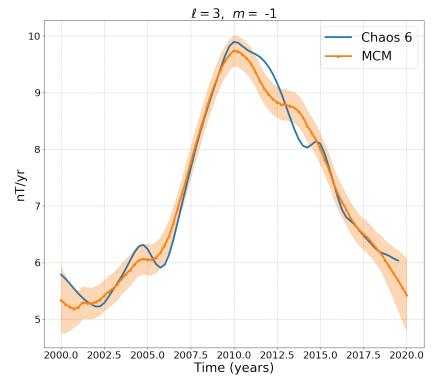


Core field

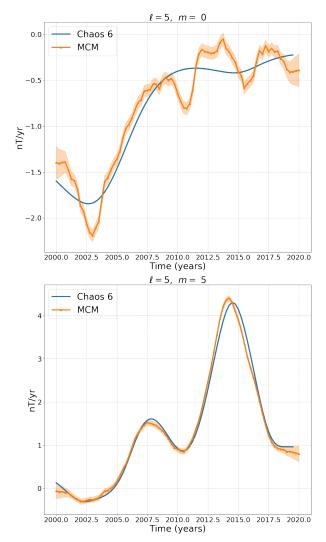
Secular Variation

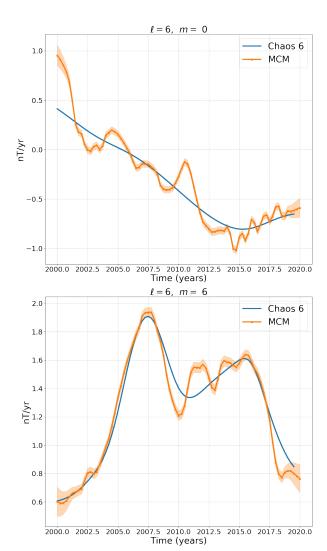
Resolution at low harmonic degrees (large scales)

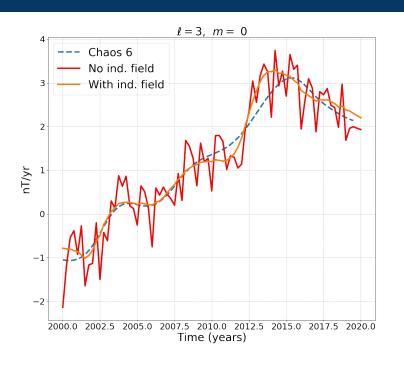


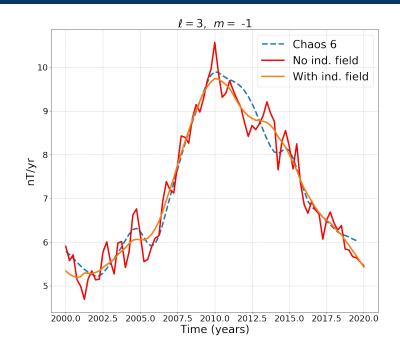


Resolution at higher harmonic degrees (small scales)









- Separation of the induced field :
 - Generated by currents induced at 400 km depth by the magnetospheric field
 - Smoother time series
 - Increase in covariance due to separation of sources
- Which features are to be attributed to the induced field?
- What is the intensity of this contribution?

Future developments

• 1st objective : IGRF 2019

- Improvement in the modelling of the induced field
 → Set better prior information
- Co-estimation of the core surface flow

Continuous assimilation of SWARM Data

Improvements in priors for the external fields (Nikolai Tsyganenko)

Thank you for your attention