Geomagnetic field modelling based on ASM-V experimental data

P. Vigneron¹, **G. Hulot¹**, J.M. Léger², T. Jager²

¹IPGP, Sorbonne Paris Cité, Université Paris Diderot - CNRS, France ²CEA-Leti, MINATEC Campus, Grenoble, France







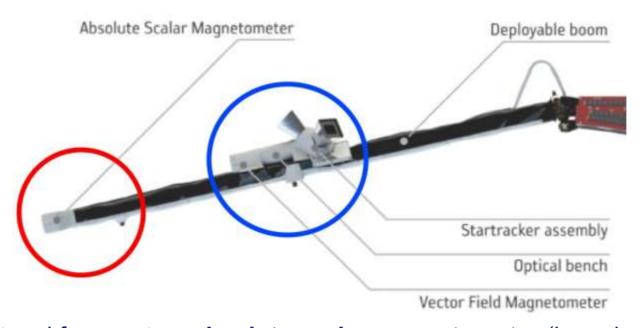








ASM-V data



The ASM is first and foremost an **absolute scalar magnetometer** (based on atomic spectroscopy of ⁴He, and relying on the Zeeman effect)

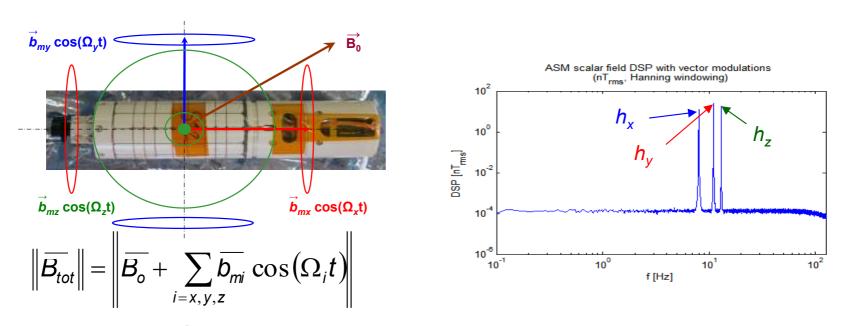
Its **nominal role** in the Swarm mission is twofold:

- Produce accurate absolute scalar measurements of the Earth's magnetic Field (1 Hz L1b scalar data)
- Provide an absolute reference for calibrating L1b vector data provided by a fluxgate vector field magnetometer (VFM, 1 Hz and 50 Hz L1b vector data)

But it can also simultaneously produce self-calibrated vector data: ASM-V data.

These data are **independent from the nominal L1b data** produced by the **VFM** instrument.

ASM vector mode principle

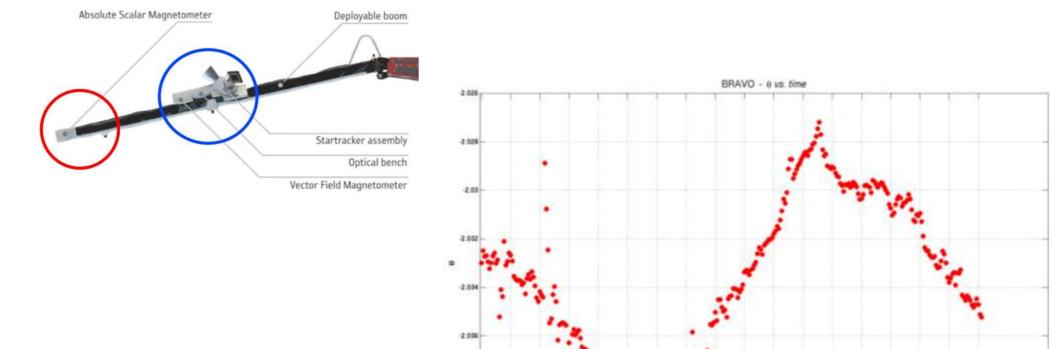


The internal sampling of the scalar sensors at 1kHz, allows the instruments to be used in conjunctions with three sets of coils to also derive vector components at 1 Hz (1 Hz "vector mode")

In this vector mode, three perpendicular coils generate periodic magnetic fields with known amplitudes (~ 50 nT) and three different known (and adjustable) frequencies beyond 1 Hz (7.92 Hz, 10.98 Hz, 12.97 Hz).

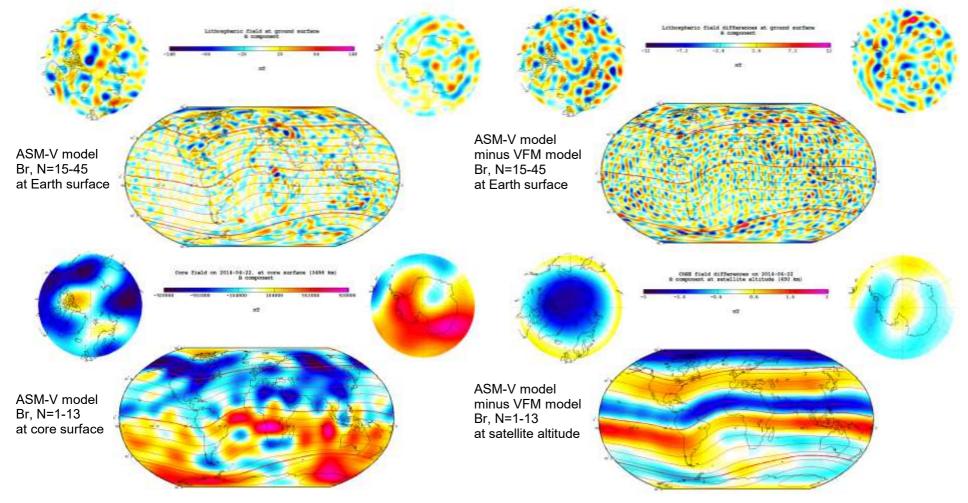
Real time analysis (with appropriate sampling rate) of the scalar field measured by the (scalar) sensor then makes it possible to measure the scalar field at 1 Hz (with nominal performance) together with all field components along the three coil axis.

Stability of the boom between the ASM and VFM/STR assembly was found to be very good



- Seasonal variations were observed in daily alignments, with amplitude of 40 arcsec, but with less than 4 arsec deformations within 10 consecutive days.
- This led to the possibility of testing ASM-V data (used together with STR data) for global field modelling.

A very good global field model could be constructed early on using ASM-V and STR data

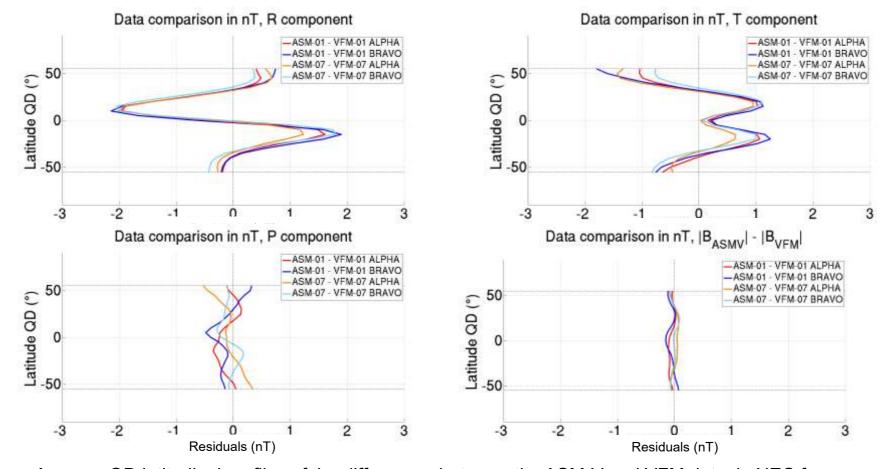


• Early model of Hulot et al. (2015), N=1-45, with SV N=1-13, using 11 months of Swarm Alpha and Bravo data

Vigneron et al, ASMV geomagnetic field modelling

• But this revealed some intriguing large scale systematic differences when compared to an analogous model computed from L1b VFM data.

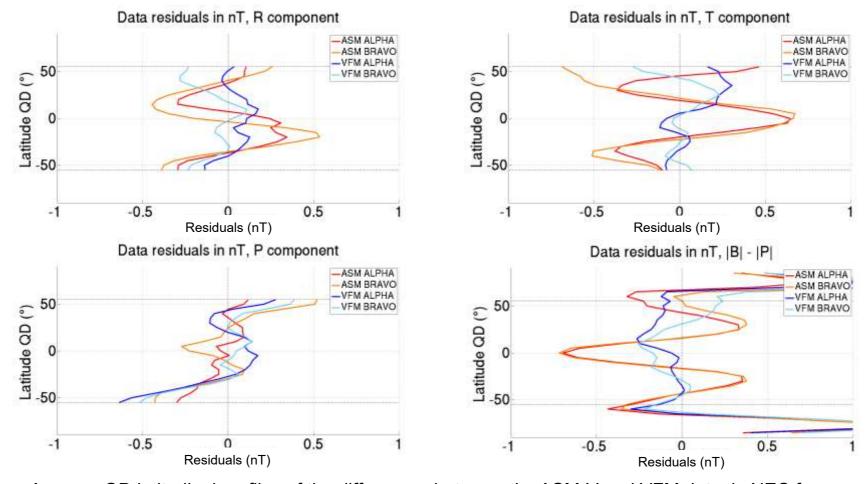
These differences arose because of disagreements between ASM-V and VFM data



Average QD latitudinal profiles of the differences between the ASM-V and VFM data in NEC frame

- Note that the differences are mainly in the B_r and B_θ coordinates -> possible up and down boom oscillations along the orbit ?
- But they also are a function of QD latitude (and NOT of orbital latitude)

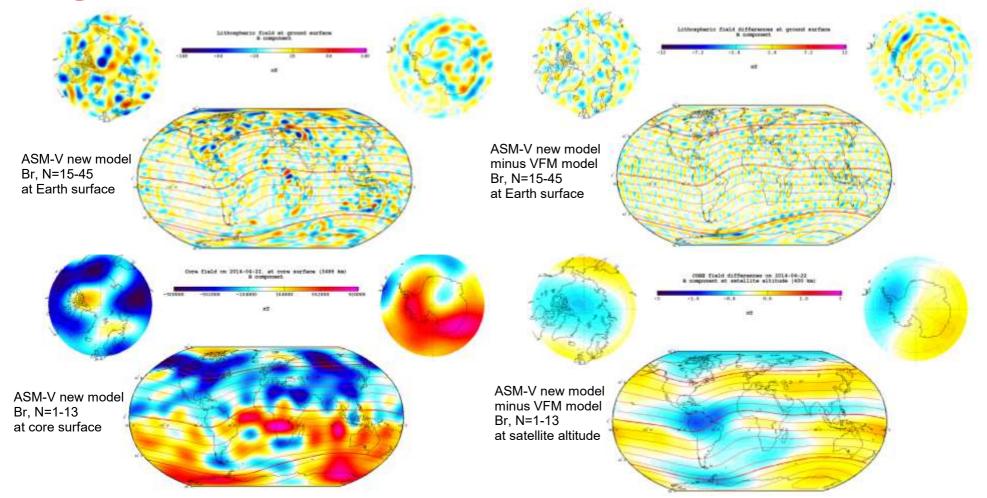
Data residuals with respect to their matching model pointed at an issue with the ASM-V data



Average QD latitudinal profiles of the differences between the ASM-V and VFM data in NEC frame

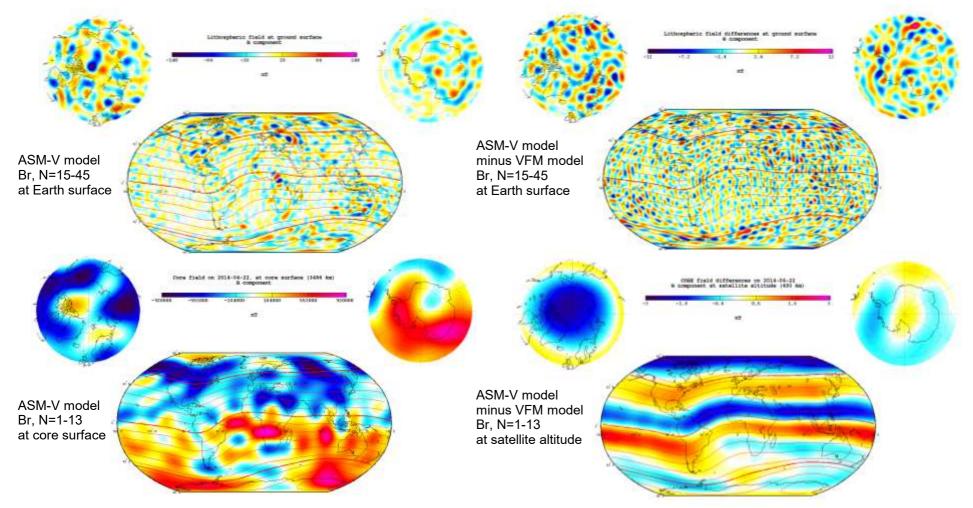
- Data residuals show a much stronger systematic signature when comparing ASM-V data to the ASM-V model
- This signature suggested a self-calibrating issue with the ASM

A Better global field model could be constructed by using recalibrated ASM vector mode (and STR) data



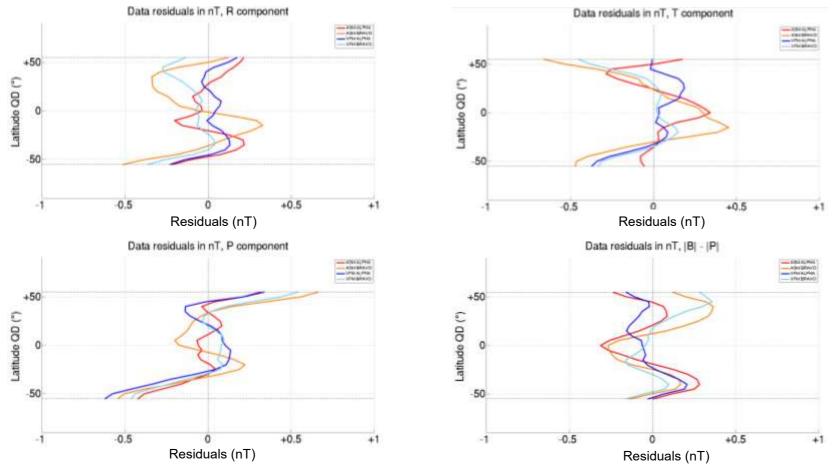
- Latest model, N=1-45, CHAOS-4 type temporal splines for N=1-13, using 4 years of Swarm Alpha and Bravo data and an improved self-calibration procedure
- Leads to much better agreement when compared to an analogous model computed from L1b VFM data (version 0503).

Recall the earlier situation with initial calibration (and using less data)



- Early model of Hulot et al. (2015), N=1-45, with SV N=1-13, using 11 months of Swarm Alpha and Bravo data
- Most of the intriguing large scale systematic differences have been corrected for and the crustal field is much improved.

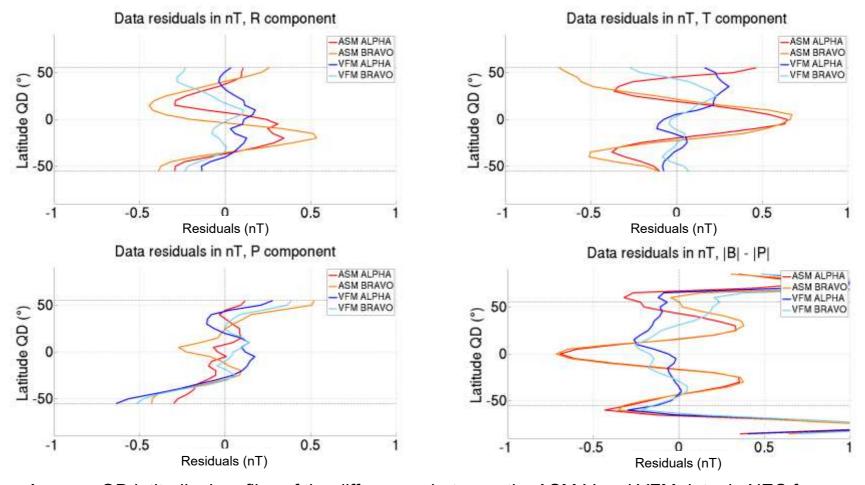
Data ASM-V residuals with respect to the ASM-V model are also improved



Average QD latitudinal profiles of the differences between the ASM-V and VFM data in NEC frame

- Data residuals show a much weaker systematic signature when comparing ASM-V data to the ASM-V model
- Recall also that boom distortion and other effects may still play a role...

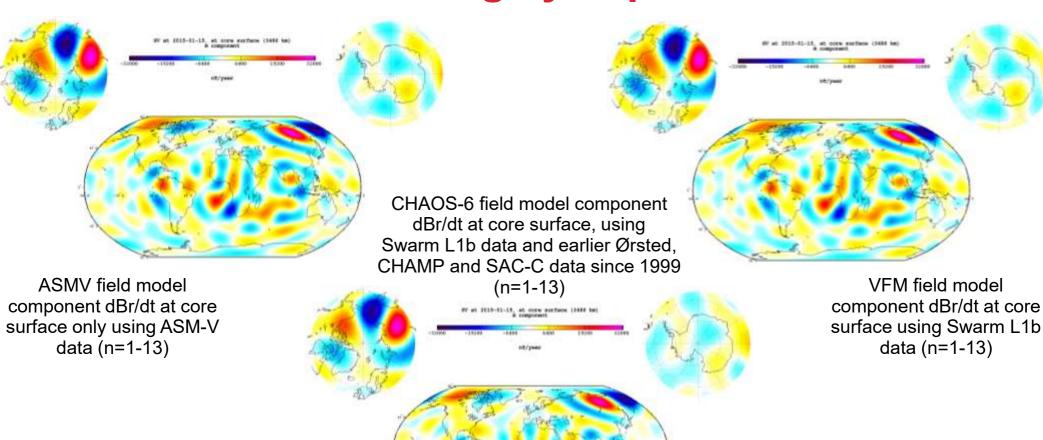
Recall the earlier situation with initial calibration (and using less data)



Average QD latitudinal profiles of the differences between the ASM-V and VFM data in NEC frame

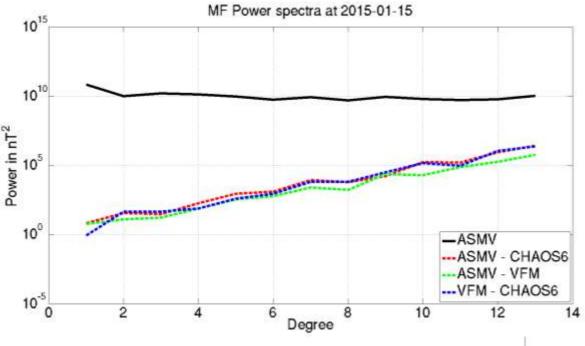
- Data residuals show a much weaker systematic signature when comparing ASM-V data to the ASM-V model
- Recall also that boom distortion and other effects may still play a role...

Recovery of Secular Variation is also hugely improved



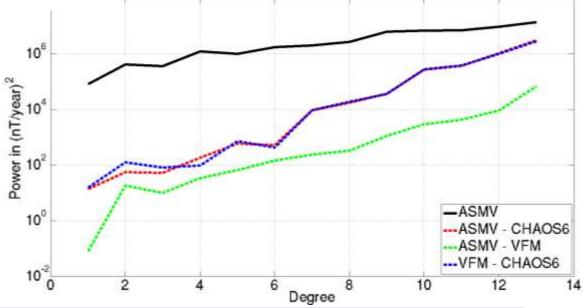
Secular Variation (here January 15, 2015), now compares very well with the SV computed from L1b VFM data (0503) and with the CHAOS-6 model (which also uses Ørsted, CHAMP and SAC-C data, Finlay et al., 2016).

Differences with respect to CHAOS-6 are now mainly due to differences in modelling strategy



ASM-V model spectrum (black) with spectra of the differences between ASM-V and CHAOS-6 models (red), ASM-V and VFM models (green), and VFM and CHAOS_6 models, all at core surface on 15/01/2015 (n=1-13)

ASM-V field SV model spectrum (black) with spectra of the differences between ASM-V and CHAOS-6 SV models (red), ASM-V and VFM SV models (green), and VFM and CHAOS_6 SV models, all at core surface on 15/01/2015 (n=1-13)

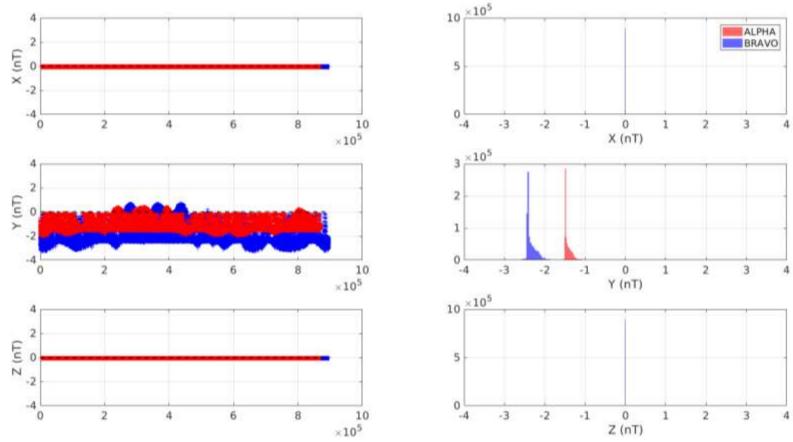


VS Power spectra at 2015-01-15

What about the dBSun issue affecting both the ASM and VFM instruments?

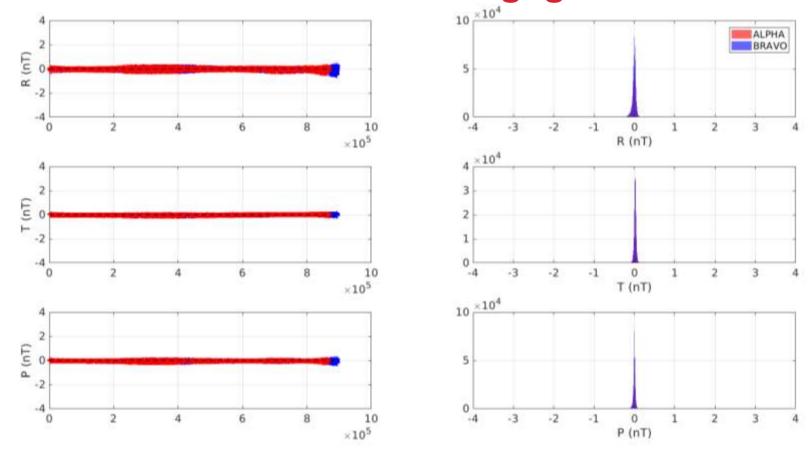
- We know dBSun perturbations are affecting both the ASM and VFM instruments (recall previous talks)
- ASM-V/VFM model comparisons shown so far in this talk were based on the assumption that the effect was only affecting the VFM instruments (we used L1b VFM data version 0503, which included such a correction to make the VFM L1b data modulus consistent with the scalar readings of the ASM). But we know this is incorrect...
- Is there a way global field modelling could help validating the part of the dBSun that is affecting the ASM instrument?
- We started looking into this and tested the impact of introducing a correction for the dBSun effect on the ASM-V data based on the model proposed by P. Brauer (using the model parameters inferred from the analysis of manoeuvres, recall talk by Vigneron and Hulot "Towards correcting ASM data for the Sun-related thermoelectric effect").
- In what follows we compare the (recalibrated) ASM-V model analysed so far with a model built in the same way but using (recalibrated) ASM-V data corrected for the dBSun effect predicted to affect it.
- How does the modelling deal with this correction?

dBSun correction predicted by the model of P. Brauer on the ASM-V data



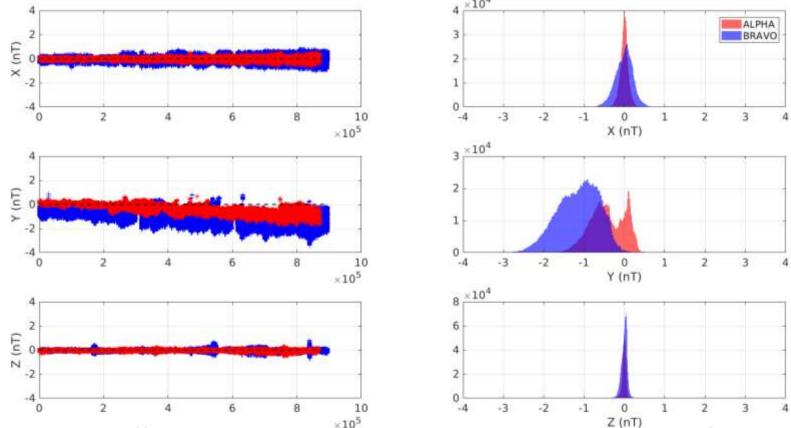
- Corrections are shown here for the X, Y, Z components in the ASM-V instrument frame of reference, for the four years of data used for the modelling
- They only affect the **Y-component** of the ASM-V data
- Because the data for modelling are selected on the night side, the correction is mainly negative
- The correction is stronger on Bravo than on Alpha

Impact on the core and lithospheric parts of the model is negligible



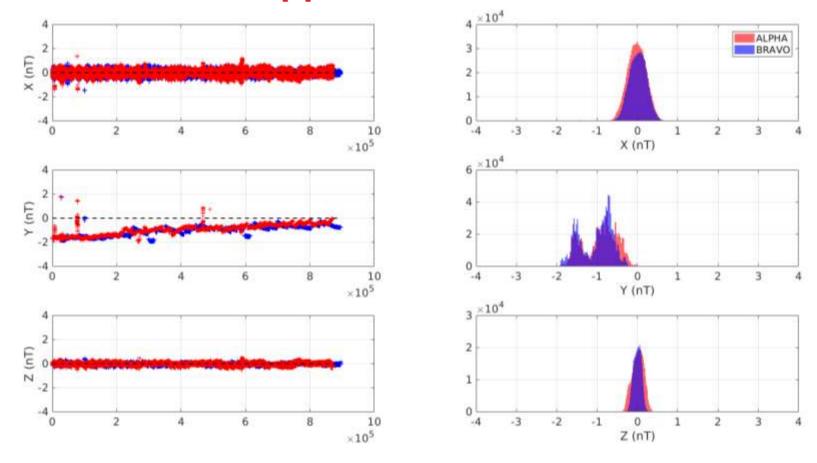
- Here, we show the differences between the B_r , B_θ , B_ϕ spherical components predicted by the original ASM-V model and those predicted by the corrected ASM-V model for the four years of data used in the modelling.
- Differences are **very small** (less than a few 0.1 nT)
- dBSun corrections are NOT affecting the core and lithospheric part of the model
- Where does the dBSun correction go?

Part of the dBSun is absorbed in the form of an apparent rotation between the ASM-V and STR frames of references



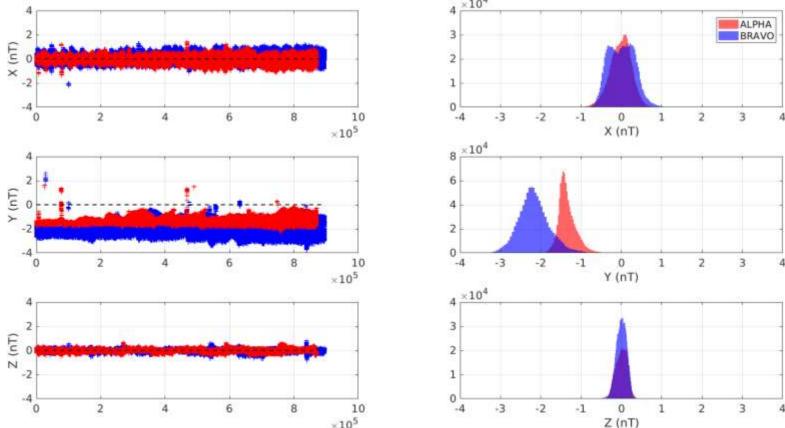
- Here, we show the differences between the X, Y, Z components in the ASM-V instrument frame of reference predicted by the original ASM-V model and those predicted by the corrected ASM-V model (only core and lithosphere).
- Differences are now commensurate with the dBSun correction and have a similar bias.
- dBSun corrections are partly mapped in the Euler angles
- Note however an intriguing trend in the Y component

Another part is absorbed in the form of an apparent external field



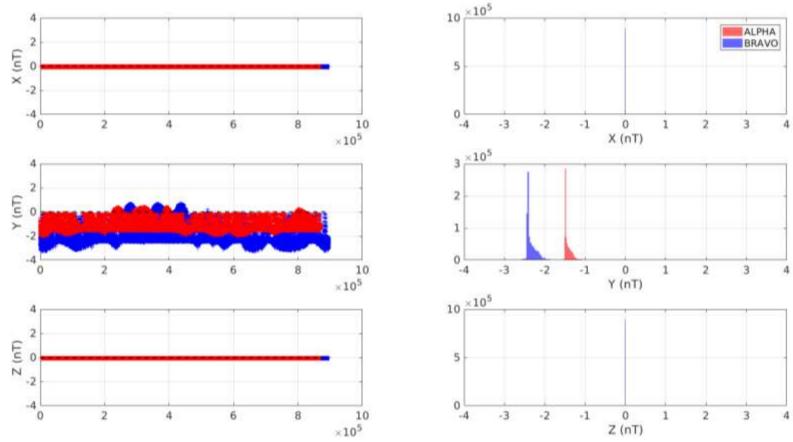
- Here, we show the differences between the X, Y, Z components in the ASM-V instrument frame of reference predicted by the original ASM-V external field model and those predicted by the corrected ASM-V external field model.
- An opposite trend is now seen in the Y component.
- dBSun corrections are also partly mapped in the external field

The combined apparent rotation and external field account for the systematics of the dBSun correction



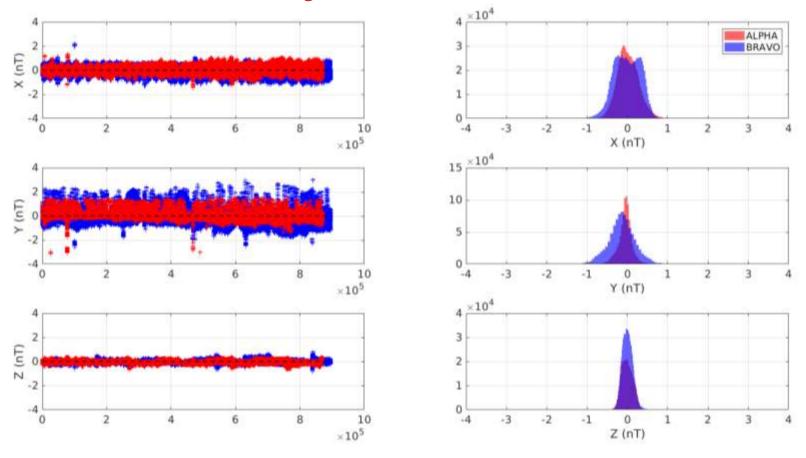
- Here, we show the differences between the X, Y, Z components in the ASM-V instrument frame of reference predicted by the original ASM-V field model and those predicted by the corrected ASM-V field model (core+lithosphere+external).
- The combined apparent rotation and external field account for the systematic negative bias of the dBSun correction on the Y component.
- Note, however, the wider distributions, which suggest that the rest of the dBSun correction must be rejected in the model residuals.

dBSun correction predicted by the model of P. Brauer on the ASM-V data



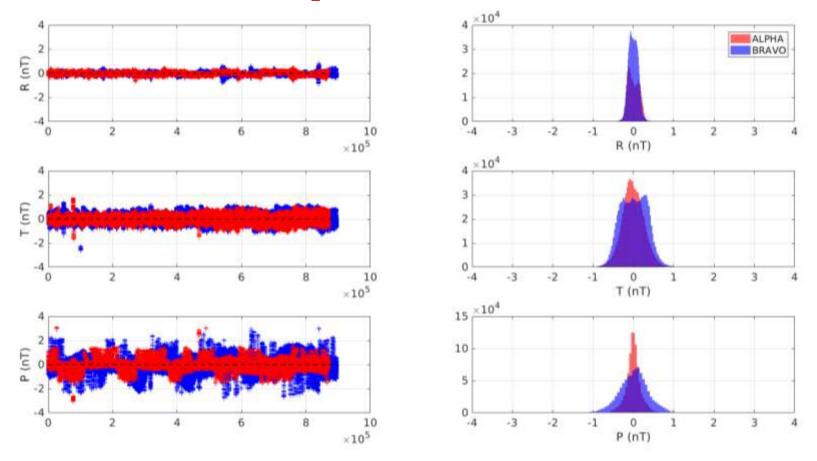
- Corrections are shown here for the X, Y, Z components in the ASM-V instrument frame of reference, for the four years of data used for the modelling
- They only affect the Y-component of the ASM-V data
- Because **the data** for modelling are **selected on the night side**, the **correction is mainly negative**
- The correction is stronger on Bravo than on Alpha

The rest of the dBSun correction is indeed rejected in the residuals



- Here, we show the differences between the X, Y, Z residuals in the ASM-V instrument frame of reference (with respect to the full core+lithosphere+external fields).
- Typical order of magnitude is 1nT on X and Y, much less on Z.

The rest of the dBSun correction is indeed rejected in the residuals



- Here, we show the differences between the B_r , B_θ , B_ϕ spherical component residuals (with respect to the full core+lithosphere+external fields).
- Typical order of magnitude is 1nT on B_{θ} and B_{ϕ} , much less on B_{r} .
- Note the pattern on the B_{ϕ} residuals, reflecting opposite effects when the satellites are up or down-going on the (selected) day side of their orbit.

Conclusion and way forward

- Geomagnetic field models built from recalibrated ASM-V data (over four years, November 2013 to November 2017) now compare very well (including the secular variation) with models built in the same way from nominal L1b VFM data, and with other more elaborate models (e.g., CHAOS-6) also taking advantage of the Charlie and gradient data and relying on additional data (Champ, Oersted, etc..), despite the higher noise levels of the ASM-V data and the more unfavourable location of the ASM with respect to the STR
- -> very encouraging results for the NanoMagSat project (see talk on Thursday)
- Investigations of the impact of the dBSun correction on the Y component of the ASM-V data suggest that the corresponding perturbation does not affect the modelled core and lithospheric fields, but is mapped into an Euler angle correction combined with an apparent external field perturbation, with a significant fraction rejected in the residuals
- -> good news for core and lithospheric field modelling ? Possibly...
- -> bad news for external field investigations ? (especially if ASM dBSun corrections are wrongly applied to L1b VFM data)
- Checking the validity of the ASM dBSun corrections with the help of geomagnetic field modelling using ASM-V data might be possible but would require a smart way of measuring the improvement brought by the correction: not possible to rely on core and lithospheric field comparisons, but looking into systematic in the residuals (on the day side, not used for modelling? Bias/Variance reduction?) could possibly help
- -> more work is needed...